

جامعة بنها - كلية العلوم - قسم الرياضيات

الفرقة الرابعة (تربية عام - رياضيات)

الفصل الدراسي الثاني

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مدرس بقسم الرياضيات بكلية العلوم

صورة من الامتحان + نموذج إجابته



Faculty of Education
Math. Dept. Benha

Fourth year Math.
Quantum Mechanics (M424)

8 / 6 / 2014
Time: 1 hour

Answer all the following questions:

1.a	Show that: the eigenvalues of a hermitian operator are pure real and its eigenvectors corresponding to unequal eigenvalues are orthogonal.
1.b	State without proof the properties of the projection operator \hat{P}_i . Let ψ_i be an orthonormal basis and the operator \hat{P}_i is defined as $\hat{P}_i\phi = \psi_i(\psi_i, \phi)$, find the eigenvalues and the corresponding eigenvectors of \hat{P}_i .
1.c	Find the eigenfunctions $\psi(x)$ and the corresponding eigenvalues of the operator: $\hat{A} = i \frac{d}{d\phi}$, $\psi(\phi) = \psi(\phi + 2\pi)$.
2.a	State the postulates of quantum mechanics.
2.b	Determine the mean value of a mechanical quantity \hat{L}_z^2 described by the hermitian operator $\hat{L}_z^2 = -\hbar^2 \frac{\partial^2}{\partial \phi^2}$ in the state $\psi(\phi) = A \sin^2 \phi$, $0 < \phi \leq 2\pi$.

انظر امتحان الكهربية الديناميكية

Dr. Khalil Mohamed

إجابة السؤال 1.a:

Proof:

In the first, we prove that the eigenvalues of a hermitian operator are pure real.

Let $\hat{A} = \hat{A}^+$ (i. e. A hermitaian) and $\hat{A}\Psi_a(x) = a\Psi_a(x)$, $\Psi_a(x) \neq 0$

$$\text{then } (\hat{A}\Psi_a, \Psi_a) = (a\Psi_a, \Psi_a) = a^* (\Psi_a, \Psi_a) = a^* \|\Psi_a\|^2 \quad (\text{i})$$

$$\begin{aligned} \text{but } (\hat{A}\Psi_a, \Psi_a) &= (\Psi_a, \hat{A}^+\Psi_a) = (\Psi_a, \hat{A}\Psi_a) = (\Psi_a, a\Psi_a) = a(\Psi_a, \Psi_a) \\ &= a\|\Psi_a\|^2 \end{aligned} \quad (\text{ii})$$

$$\text{from i and ii leads to } a^* \|\Psi_a\|^2 = a\|\Psi_a\|^2 \Rightarrow (a^* - a)\|\Psi_a\|^2 = 0$$

$\therefore \Psi_a \neq 0 \Rightarrow a^* - a = 0 \Rightarrow a^* = a$ i.e the eigenvalues are pure real

second, suppose

$$\hat{A}\Psi_1(x) = a_1\Psi_1(x), \Psi_1(x) \neq 0 \quad \text{and} \quad \hat{A}\Psi_2(x) = a_2\Psi_2(x), \Psi_2(x) \neq 0; a_1 \neq a_2$$

$$\text{since } (\Psi_1, \hat{A}\Psi_2) = (\Psi_1, a_2\Psi_2) = a_2(\Psi_1, \Psi_2) \quad (\text{iii}) \quad \text{also}$$

$$(\Psi_1, \hat{A}\Psi_2) = (\hat{A}\Psi_1, \Psi_2) = (a_1\Psi_1, \Psi_2) = a_1(\Psi_1, \Psi_2) \quad (\text{iv})$$

$a_1 = a_1^*$ because a_1, a_2 are real then from (iii) and (iv) we have

$$a_2(\Psi_1, \Psi_2) = a_1(\Psi_1, \Psi_2) \Rightarrow (a_2 - a_1)(\Psi_1, \Psi_2) = 0 \quad \text{but } a_1 \neq a_2$$

$\Rightarrow (\Psi_1, \Psi_2) = 0$ i.e. the eigenvectors are orthogonal.

إجابة السؤال 1.b:

Proof:

The properties of the projection operators \hat{P}_i are:

$$\text{i- } \hat{P}_i \text{ is linear} \quad \text{ii- } \hat{P}_i \text{ is hermitian} \quad \text{iii- } \hat{P}_i^2 = \hat{P}_i \quad \text{iv- } \hat{P}_i \hat{P}_j = \hat{P}_j \hat{P}_i = \delta_{ij} \hat{P}_i$$

$$\text{v- } \sum_i \hat{P}_i = \hat{1}$$

The eigenvalues of the projection operators : Let $\hat{P}_i \varphi_\lambda = \lambda \varphi_\lambda$, $\varphi_\lambda \neq 0$

$$\text{and since } \hat{P}_i \text{ is linear and } \hat{P}_i^2 \varphi_\lambda = \hat{P}_i(\hat{P}_i \varphi_\lambda) = \hat{P}_i(\lambda \varphi_\lambda) = \lambda(\hat{P}_i \varphi_\lambda) = \lambda^2 \varphi_\lambda$$

$$\text{and also } \hat{P}_i^2 = \hat{P}_i \Rightarrow (\lambda^2 - \lambda)\varphi_\lambda = \lambda(\lambda - 1)\varphi_\lambda = 0, \varphi_\lambda \neq 0 \Rightarrow \lambda = 0, 1.$$

** The eigenvectors of the projection operators:

when $\lambda = 0$, the corresponding eigenvector is φ_0 then $\hat{P}_i \varphi_0 = \psi_i(\psi_i, \varphi_0) = 0\varphi_0 = 0$,

and ψ_i basis then $(\psi_i, \varphi_0) = 0 \Rightarrow \varphi_0 = \sum_{j \neq i} \alpha_j \psi_j$ where we can write φ_0 by the basis ψ_i

when $\lambda = 1$, the corresponding eigenvector is φ_1 then $\hat{P}_i \varphi_1 = \psi_i(\psi_i, \varphi_1) = 1\varphi_1 = \varphi_1$, and ψ_i basis then $(\psi_i, \varphi_1) = k \neq 0 \Rightarrow \varphi_1 = k\psi_i$ (i.e. linearly dependent).

إجابة السؤال 1.c:

To obtain the eigenfunctions and the eigenvalues for the given operator, we suppose

$$\hat{A}\psi = \lambda\psi, \psi \neq 0 \Rightarrow i\frac{d}{d\varphi}\psi = \lambda\psi \therefore \frac{d}{d\varphi}\psi(\varphi) = -i\lambda\psi(\varphi) \Rightarrow \int \frac{d\psi}{\psi} = i\lambda \int d\varphi$$

$$\Rightarrow \ln\left(\frac{\psi}{B}\right) = i\lambda\varphi \Rightarrow \psi = Be^{i\lambda\varphi} \quad \text{from the condition} \quad \psi(\varphi) = \psi(\varphi + 2\pi)$$

$$\text{we have } Be^{-i\lambda\varphi} = Be^{-i\lambda(\varphi+2\pi)} = Be^{-i\lambda\varphi} e^{-2i\pi\lambda} \Rightarrow e^{-2i\pi\lambda} = 1 \therefore \cos(-2\pi\lambda) + i\sin(-2\pi\lambda) = 1$$

$$\Rightarrow \cos(2\pi\lambda) - i\sin(2\pi\lambda) = 1 \text{ by comparison } 2\pi\lambda = 2n\pi, \quad n = 0, 1, 2, \dots \quad \lambda = n \text{ and the eigenfn.}$$

$$\psi(\varphi) = Be^{-in\varphi}, \quad n = 0, 1, 2, \dots$$

إجابة السؤال 2.a:

*The postulates of quantum mechanics are:

1)- Postulate I: Every physical state of a dynamical system (a particle) is represented at a given instant of time t by normed vector $|\psi\rangle_t$ in H . It is assumed that the state vector contains all the information which one can know about the state of the system at that instant of time. ψ and $e^{i\delta}\psi$ where $\delta^* = \delta$ represent the same physical state.

2)- Postulate II: To every dynamical variable A there corresponds an observable \hat{A} . The observable \hat{x} and \hat{p} must satisfy $[\hat{x}, \hat{p}] = i\hbar$. The rules for constructing the observable \hat{A} corresponding to the dynamical variable A , in the x -rep are as follows:

$$(i) x \rightarrow \hat{x} = x, \quad t \rightarrow \hat{t} = t, \quad p \rightarrow \hat{p} = -i\hbar \frac{d}{dx}$$

$$(ii) A(x, p, t) \rightarrow \hat{A} = A(x, -i\hbar \frac{d}{dx}, t).$$

3)- Postulate III: If a particle is in state $|\psi\rangle_t$, a measurement of a dynamical variable A which is represented by the observable \hat{A}

$$\hat{A}|\varphi_n\rangle = a_n|\varphi_n\rangle, \quad \langle\varphi_n|\varphi_m\rangle = \delta_{nm}, \quad \hat{1}_a = \sum_i |\varphi_i\rangle\langle\varphi_i| \text{ will}$$

*yield one of the eigenvalues a_i with probability

$$\rho_\psi(a_i) = \frac{|\langle\varphi_i|\psi\rangle|^2}{\langle\psi|\psi\rangle}$$

** If the result of measurement is a_k , then the state of the system will change from

$|\psi\rangle$ to $|\varphi_k\rangle$ as a result of measurement.

4)- Postulate IV: The state function $\psi(x, t)$ describing the state of a dynamical system whose Hamiltonian is \hat{H} obeys the following "Schrodinger time-dependent" equation

$$i\hbar \frac{\partial}{\partial t} \psi(x, t) = \hat{H} \psi(x, t)$$

إجابة السؤال 2.b:

$\therefore \psi(\varphi) = A \sin^2(\varphi)$ describe the system i.e. normed

$$\therefore \|\psi(\varphi)\|^2 = 1 \Rightarrow \int_0^{2\pi} |A|^2 \sin^4(\varphi) d\varphi = 1 \Rightarrow |A|^2 \int_0^{2\pi} \sin^4(\varphi) d\varphi = 1$$

$$\therefore \sin^2(\varphi) = \frac{1}{2}(1 - \cos(2\varphi)), \quad \cos^2(\varphi) = \frac{1}{2}(1 + \cos(2\varphi)) \therefore \frac{|A|^2}{4} \int_0^{2\pi} (1 - \cos(2\varphi))(1 + \cos(2\varphi)) d\varphi$$

$$= \frac{|A|^2}{4} \int_0^{2\pi} (1 - 2\cos(2\varphi) + \cos^2(2\varphi)) d\varphi = \frac{|A|^2}{4} \int_0^{2\pi} (1 - 2\cos(2\varphi) + \frac{1}{2}(1 + \cos(4\varphi))) d\varphi$$

$$= \frac{|A|^2}{4} \int_0^{2\pi} (\frac{3}{2} - 2\cos(2\varphi) + \frac{1}{2}\cos(4\varphi)) d\varphi = \frac{|A|^2}{4} [\frac{3}{2}\varphi - \sin(2\varphi) + \frac{1}{8}\sin(4\varphi)]_0^{2\pi}$$

$$\therefore \frac{|A|^2}{4} [\frac{3}{2}(2\pi) - 0 + \frac{1}{8}(0) - 0 + 0 - 0] = \frac{3\pi |A|^2}{4} = 1 \therefore |A|^2 = \frac{4}{3\pi} \Rightarrow A = \frac{2}{\sqrt{3\pi}}$$

$$\therefore \psi(\varphi) = \frac{2}{\sqrt{3\pi}} \sin^2(\varphi), \quad 0 < \varphi < 2\pi$$

$$\therefore \langle L_z^2 \rangle_\psi = \langle \psi | L_z^2 | \psi \rangle = \int_0^{2\pi} \frac{2}{\sqrt{3\pi}} \sin^2(\varphi) \cdot (-\hbar^2 \frac{d^2}{d\varphi^2} \frac{2}{\sqrt{3\pi}} \sin^2(\varphi)) d\varphi$$

$$= \frac{4}{3\pi} (-\hbar^2) \int_0^{2\pi} \sin^2(\varphi) \cdot \frac{d^2}{d\varphi^2} \sin^2(\varphi) d\varphi = \frac{-4\hbar^2}{3\pi} \int_0^{2\pi} \sin^2(\varphi) \cdot [2(\cos^2(\varphi) - \sin^2(\varphi))] d\varphi$$

$$= \frac{-4\hbar^2}{3\pi} \int_0^{2\pi} \sin^2(\varphi) \cdot 2\cos(2\varphi) d\varphi = \frac{-4\hbar^2}{3\pi} \int_0^{2\pi} \frac{1}{2} (1 - \cos(2\varphi)) \cdot 2\cos(2\varphi) d\varphi$$

$$= \frac{-4\hbar^2}{3\pi} \int_0^{2\pi} (\cos(2\varphi) - \cos^2(2\varphi)) d\varphi = \frac{-4\hbar^2}{3\pi} \int_0^{2\pi} (\cos(2\varphi) - \frac{1}{2}(1 + \cos(4\varphi))) d\varphi$$

$$= \frac{-4\hbar^2}{3\pi} [\frac{1}{2}\sin(2\varphi) - \frac{1}{2}\varphi - \frac{1}{8}\sin(4\varphi)]_0^{2\pi} = \frac{-4\hbar^2}{3\pi} [0 - \frac{1}{2}2\pi - 0] = \frac{4\hbar^2}{3}$$
